

IN THE CLAIMS:

Please amend the claims as follows:

1. (Currently Amended) An industrial robot, comprising:

a robot arm including a plurality of first arm components swingably connected to one another; and

a base to which one of the first arm components at a base-side end of the robot arm is connected,

wherein the first arm component is driven by a thrust of a rod which has a thread groove in its outer surface, the rod being axially moved by rotating a nut meshed with the rod.

wherein each of the first arm components has a connector which is detachably connected to a neighboring one of the first arm components, and

the connector is connectable to a replacement second arm component in place of the neighboring first arm component.

2. (Currently Amended) An industrial robot, comprising:

a robot arm including a plurality of first arm components swingably connected to one another; and

a base to which one of the first arm components at the base-side end of the robot arm is connected,

wherein the first arm component is driven by a thrust of a rod which has a thread groove in its outer surface, the rod being axially moved by rotating a nut meshed with the rod.

wherein each of the first arm components has a connector which is detachably connected to a neighboring one of the first arm components, and

the connector is connectable to an additional second arm component added to the robot arm and included in the robot arm together with the first arm components.

3. (Original) The industrial robot of claim 1 or 2, wherein the length of the second arm component in its arm axis direction is different from the length of the first arm component in its arm axis direction.
4. (Original) The industrial robot of claim 1 or 2, wherein: the second arm component is divided into a base-side part and a tip-side part at an axially intermediate position; and the second arm component has rotation means for rotating the tip-side part around its arm axis relative to the base-side part.
5. (Original) The industrial robot of claim 1 or 2, wherein the second arm component includes a movable member and a moving device for moving the movable member in the arm axis direction of the second arm component.